X-Ray Image Analysis

Francesco Damiani

Istituto Nazionale di Astrofisica Osservatorio Astronomico di Palermo



X-Rays from Star Forming Regions

Palermo, May 20, 2009



Introduction:

X-ray images in selected time- or energy ranges; time- and energy-filtering of background; common features of detectors: gaps and dithering; spatially variable PSF/resolution; photon pile-up; vignetting and exposure maps; particle detection and afterglows

Historical perspective:

from Einstein IPC to Chandra HRC/ACIS images; going to extremely low background-per-resolution-element; deep images and source confusion.

Techniques:

local (cell) and map detect; matched filters and wavelet detection; analogies with optical techniques.

Details of wavelet technique:

Multi-scale detection; edges and gaps; multi-scale background; threshold calibrations and confidence levels for source existence; count-rate and size estimation; errors; PSF corrections; artifacts for bright sources.



Palermo, May 20, 2009



X-ray images from binned position lists:

- Opportunity to select time intervals or energy bands of astrophysical interest
- Ability to reject background "optimally" for your scientific aims
- Background filtering on time, energy, event type







Background filtering on time, energy, event type:

→ removal of:
(1) detector noise, particles, bad pixel
(2) high-background time segments

e.g. V410 Tau XMM-Newton EPIC-pn full-field background lightcurve...





...and images, with increasing degrees of filtering







Palermo, May 20, 2009 F

Detector shadows/support ribs

Example: ROSAT PSPC – modulated by "wobbling", to obtain only partially underexposed regions under the ribs (and to prevent bright point sources from "burning" the detector...):

→ reduced information under ribs

Example: XMM EPIC/pn – no wobbling, zero exposure between CCD chips:

→ no information in gaps

In both cases a problem for reliable source detection!









Mirror+detector PSF:

- Strong variation with off-axis distance (e.g. a factor of ~10 for Chandra ACIS-I):
- Choice of detection cell/scale size is very important
- Main factor to determine off-axis limit sensitivity (reduced source/background contrast)



Telescope vignetting:

- Information stored in exposure map (shown for XMM EPIC-pn):
- Slight energy dependence of decrease
- Minor factor for decreased off-axis sensitivity







Other disturbances

- Photon pile-up: more than one X-ray photon/pixel/CCD frame
- ⇒ detected as one event, with wrong shape (i.e. pattern or grade), and wrong (cumulated) energy. Kind of "saturated", unusable pixels, in the core of very bright point sources (e.g. Θ¹ Ori):
- Out-of-time events (in CCD images of bright sources): true X-ray events, recorded while the CCD is being read, and assigned to a wrong position along the same CCD column.
- Particle detection, and "afterglow" events: CCD pixels are hit by energetic particles, and generated electrons are read over many (2-7) readout frames, mimicking faint sources (often smaller than the PSF), with impulsive variability:









Historical perspective: 30 years of cluster imaging

- Einstein Observatory IPC (Imaging Proportional Counter) and HRI (High Resolution Imager) – 1978-1981
- ROSAT PSPC (Position Sensitive Proportional Counter) and HRI (High Resolution Imager) – 1990-1999
- XMM-Newton EPIC (European Photon Imaging Camera), with MOS1, MOS2 and pn detectors – 2000-today
- Chandra HRC (High Resolution Camera) and ACIS (Advanced CCD Imaging Spectrometer) – 2000-today
- Other satellites (e.g. ASCA 1993-2000) observed individual bright, young stars (but PSF too wide for proper cluster imaging)

A noticeable sensitivity improvement with time: four orders of magnitude!







ROSAT/PSPC



Einstein/IPC



Einstein/HRI







Palermo, May 20, 2009

A few views of Orion Trapezium, with increasing detail



Chandra ACIS and HRC images:

- Best spatial resolution ever in X-rays: on-axis PSF FWHM = 0.5"
- Very low background (detector + sky): 1-2 · 10⁻⁶ counts/sec/sq.arcsec
 - ⇒ in a resolution element of 1"x1" and 100 ksec exposure, one has a typical background of 0.1-0.2 counts!
 - ⇒ very few source photons needed to have a statistically significant detection
- However: number of resolution elements
 is huge ⇒ threshold cannot be set too low
- And: not straightforward to actually measure such a low background locally

Example: 2'x2', center of ACIS FOV, 100-ksec exposure, inner circle radius = 2.5" (full PSF inside) outer circle radius = 7.5" \Rightarrow poor background measurement \Rightarrow ill-defined threshold







Chandra deep imaging:

- Thanks to very high spatial resolution and low background, exposures lasting ~ 1-2 Msec can be usefully made, e.g. COUP in Orion, Galactic Center, Chandra Deep Fields North and South, Antennae (extragalactic)...
- Only with the longest exposure times, a background-limited regime is reached at field center
- Most important practical limit is source confusion. This is reached sooner (i.e. already with shorter exposures) in dense clusters than in "average" fields such as those of CDFS, CDFN.
 - ⇒ young, dense clusters are a <u>real challenge</u> for source detection methods!

Examples:

(left): core of Mon R2 (800 pc), 4'x4':

(right): core of Tr 14 (~2 kpc), 2'x2':









Techniques for X-ray source detection:

- Sliding-cell (with local or mapped background)
- Maximum-likelihood
- Wavelets

Advantage of Local sliding-cell: simpler (to implement and understand!), but too much w.r.t. the image complexity...

Wavelets enable very efficient detection of sources, since useful information in current X-ray images is inherently multi-scale (non-uniform PSF, diffuse sources).

Different flavors of wavelet detection methods are available for the same instrument datasets, e.g. *wavdetect* (developed at Chicago/CfA), and *pwdetect* (developed at INAF/OAPA). Of this latter, there is also a version working on XMM data, called *pwxdetect*.

Pw(x)detect has been used in major X-ray projects, both stellar and extragalactic: COUP, XEST, DROXO, COSMOS...





Basics of sliding-cell method:

- A square cell (n x n pixels) is defined as the source photons extraction region (let the number of counts in it be = 5).
- A concentric, larger square is used to extract the source background (with total counts = B).
- The net source counts $N = S B \times A_B / A_S$ (with $A_{S'} A_B$ being areas of S and B regions, respectively) are computed.
- As a refinement, the PSF knowledge permits to compute the fraction of total source counts falling in S, and also those residual source counts falling in B, and therefore corrective coefficients to S and B.
- The signal/noise ratio SNR is computed at the cell position.
- The detection cell is slided across the image in steps of 1/3 its size, a map of SNR is computed, and local maxima (sources) are found.
- The value of Image background used to define thresholds for detection is derived either from the local "annulus" around the source position, or from a pre-determined background spatial map.
- Optionally, the procedure is repeated with different cell sizes *n*.



Palermo, May 20, 2009



What are wavelets?

Many answers possible...

Shortly, wavelets allow a "mixed" representation of data, in terms of "conjugate" variables (e.g. time and frequency, or space and spatial frequency).

Fourier analysis tells us that each such pair of quantities cannot be <u>simultaneously</u> determined (an "Heisenberg uncertainty principle" in data analysis), <u>with arbitrarily high accuracy</u>.

It is nevertheless common experience that we e.g. hear sounds having *fairly definite* frequencies over *finite time intervals*. We do not need waiting forever before perceiving a definite frequency!

Analogous quantities in spatial domain are *positions* and *sizes* (or generally shapes) of objects in images: a wavelet transform (unlike Fourier transforms) permits both properties to be studied at the same time.

Since a wavelet transform (WT) is able to "know" the source size/shape, there is no need to either assume a PSF, nor to set a fixed extraction cell size. Large PSF variations across the FOV are easily handled by WT. Source apparent sizes are automatically derived in the detection process.



alermo, May 20, 2009



A little mathematics for WTs:

A WT is computed as a *convolution* of the original image f(x,y) with a suitable function g(x,y,a), called *generating wavelet*.

$$w(x, y, a) = \iint g\left(\frac{x - x'}{a}, \frac{y - y'}{a}\right) f(x', y') dx' dy'$$

Here *a* is the "scale" parameter (assumed to be the same for both *x* and *y*). Therefore, the WT is a function of both space *and* scale, w(x,y,a).

The g(x,y,a) must be bounded, square-integrable in spatial domain, must have zero mean and compact support.

A commonly used form for g(x,y,a) is the so-called <u>Mexican-Hat</u>:

$$g\left(\frac{x}{a},\frac{y}{a}\right) \equiv g\left(\frac{r}{a}\right) = \left(2 - \frac{r^2}{a^2}\right)e^{-r^2/2a^2} \left(r^2 = x^2 + y^2\right)$$



...which despites tending rapidly to zero for increasing *r*, has no compact support and is not "mathematically" a true wavelet! But is enough so for our purposes...





In addition, the Mexican-Hat generating wavelet has the property of "mimicking" a typical "gaussian-like" PSF: as such the WT is a kind of "matched filter", extracting useful information from an image by a proper weighting. Its analogues in optical data analysis are gaussian-weighted photometric extraction, or optimal extraction for fiber spectroscopy.

Using this generating wavelet, the WT will be:

- Zero for a flat background (as for any g(x,y,a))
- Zero for a uniform-gradient background
- Very sensitive to 2^{nd} derivative of data f(x,y) (in fact, is its smoothed laplacian):

$$w(x, y, a) = \iint \left(2 - \frac{r^2}{a^2}\right) e^{-r^2/2a^2} f(x', y') dx' dy'$$
$$= -a^2 \iint e^{-r^2/2a^2} \left(\frac{\partial^2 f}{\partial x'^2} + \frac{\partial^2 f}{\partial y'^2}\right) dx' dy'$$

...and any image edge has an *horribly large* 2^{nd} derivative! \rightarrow handle with caution





WT of a gaussian source plus flat background:

$$w(r, a) = \frac{N_{\rm src}}{(1 + \sigma_{\rm src}^2/a^2)^2} \left(2 - \frac{r^2}{a^2 + \sigma_{\rm src}^2}\right) e^{-r^2/2(a^2 + \sigma_{\rm src}^2)}$$

i.e., as a function of <u>space</u> (x,y):



...and as a function of <u>scale</u> a, at spatial peak (r=0):



$$w_{\text{peak}}(a) = \frac{2N_{\text{src}}}{(1 + \sigma_{\text{src}}^2/a^2)^2}.$$

Also useful is the function $y(a) = w_{peak}(a)/a$ peaking at $a_{max} = \sqrt{3} \sigma_{src}$

→ A range of scales near a_{max} must be explored to find source properties



Palermo, May 20, 2009

Image background and WT noise

- The WT of a flat background has zero *expected value*, but non-zero *fluctuations*
- Such fluctuations translate into thresholds in WT space, to avoid spurious detections with a desired confidence level
- The probability distribution of these WT fluctuations is highly non-Gaussian (and non-analytic) for a low-intensity background – best modeled through simulations
- The relevant parameter is defined as q = bg x a², i.e. the number of background counts per squared scale
- This gives a "local" confidence value (n-σ significance) for a detection, but...



constellation



Palermo, May 20, 2009

- ...don't forget the often very high number of resolution elements (~ 1 million) in high-resolution images!
- → we better speak of the number of full-field spurious detections (calibrated via simulations, for various total background values), e.g.:





Palermo, May 20, 2009



A block diagram for *pwdetect* (and *pwxdetect*) algorithm:







An example: **EPIC pn image and its WT** at a particular scale *a*: N.B. the image is interpolated over gaps to avoid strong background discontinuities!



Background computation:

- **1**. adaptive smoothing (with Gaussian $\sigma = \sigma_{PSF}$)
- 2. Median filter (over cells of size \sim scale a)
- After first pass of detection, interpolate over source positions (using a "swiss-cheese" mask), also usable to study diffuse emission
- 4. Repeat step 2.
- 5. For very low background (Chandra), a Poisson distribution is fit to the local image histogram



Palermo, May 20, 2009





WT of image gaps and edges

WT detection on simulated background images + *instrument exposure variations*

On *raw* ROSAT/PSPC count image: lots of *spurious detections* near gaps and edge On *exposure corrected* image: spurious detections *uniformly distributed* (~ density of resolution elements)



Use of exposure map is mandatory to deal with these nonuniformities.

The WT is computed on count-rate images, and its statistics suitably modified.





Real sources near gaps

Completely *black gaps* (XMM EPIC) are hard to deal with (example: σ Ori cluster):



...but combining EPIC MOS and pn datasets before detection helps to find good source positions near gaps!





Palermo, May 20, 2009

Source properties:

- Detection (maximum) significance and corresponding scale
- Position + error
- Count rate + error
- Apparent size + error
- Background count rate

Detection significance is determined independently of assumptions on source shape. All other parameters are derived from fitting the "theoretical" $w_{peak}(a)$ profile for a Gaussian source to that found in the WT. Error computation is highly non-trivial.

Source count-rates and sizes are simultaneously determined, under the only hypothesis of a Gaussian source shape. Corrections for a non-Gaussian instrument PSF are later applied to count rates.

 At very low background levels, common to Chandra images, sources may be reliably detected with very few counts (4-6), at high confidence levels (e.g. 5 σ, or 99.99994%), but have count-rates uncertain even by 50%!

→ Probability of existence and accuracy of count-rates (fluxes) are <u>two different problems</u>





Example of WT of ROSAT/PSPC PSF

as modeled by Hasinger et al. (1993): near the WT peak, the Gaussian component is dominant...

...but this is not so for all instruments, and accurate calibrations must be (and have been) made in every case!

After detection, you may also choose to compute fluxes using more "instrument-PSF-optimized" tools, like e.g. *acis_extract.*







Residual problems:

- Spurious detections along out-of-time event trails for bright sources
- Spurious detections in the PSF wings around very bright point sources
- Misbehaviour for highly distorted non-radially symmetrical PSF, near outer image border







Some comparison

Wavelets (red circles) vs. another method (green squares), ROSAT/PSPC data on SN1987a in LMC:

Wavelets perform better in a crowded field, and near obscuring ribs!



For more information see:

Damiani,F. et al. 1997, ApJ, 483, 350 *(wavelets)* Damiani,F. et al. 1997, ApJ, 483, 370 Harnden,F.R.,jr. et al. 1984, SAO special report 393 *(sliding-cell)* Cruddace, R., et al. 1988, in Astronomy from Large Databases, ESO *(max-likelihood)*





Sample pwdetect session

(...is not as terrible as you maybe expect!)

prompt> ./pwdetect_1.3.2.lnx Thu Jul 26 19:03:22 2001

> Welcome to PWDETECT V1.2 Palermo Wavelet Detect for CHANDRA data

Input file name (event_list.fits): Final threshold significance for detection (5.2): Maximum wavelet scale (arcsec) [powers of sqrt(2)] (16): Detection at Maximum Scale only (y/n) (n): Additional edge margin (arcsec) (7): Relative exposure threshold (0-1, recommended: 0.9) (0.9): ACIS single chip mode flag (0=Full ACIS-I, 1=Single Chip) (0): ACIS single chip Identifier (0 to 9) (0): Output source list filename root (det): Output background filename root (bkgmap): Output Log file name (det_log): Live show (1=yes, 0=no) ? (0): Exposure map file name (exposure_map_1.0keV.fits):

Reading exposure map: exposure_map_1.0keV.fits ...done

initial threshold = 4.00 sigmas final threshold = 5.20 sigmas Detector is ACIS-I ... reading data ... successfully read 20295 events performing detection at 11 scales, from 0.50 to 16.00 arcsec, in logarithmic steps by a factor sqrt(2)







Palermo, May 20, 2009

computing background image... done 51 sources at scale = 0.50 arcsec 69 sources at scale = 0.71 arcsec 69 sources at scale = 1.00 arcsec 98 sources at scale = 1.41 arcsec 113 sources at scale = 2.00 arcsec 143 sources at scale = 2.83 arcsec 143 sources at scale = 4.00 arcsec 118 sources at scale = 5.66 arcsec 105 sources at scale = 8.00 arcsec 86 sources at scale = 11.31 arcsec 63 sources at scale = 16.00 arcsec computing best source properties ... done computing background image update ... done 51 sources at scale = 0.50 arcsec 69 sources at scale = 0.71 arcsec 69 sources at scale = 1.00 arcsec 100 sources at scale = 1.41 arcsec 113 sources at scale = 2.00 arcsec 146 sources at scale = 2.83 arcsec 148 sources at scale = 4.00 arcsec 121 sources at scale = 5.66 arcsec 106 sources at scale = 8.00 arcsec 91 sources at scale = 11.31 arcsec 66 sources at scale = 16.00 arcsec computing best source properties ... done Total number of detected sources = Nominal effective area (cm²) = 286.6157 Thu Jul 26 19:10:46 2001 total elapsed time: 444 sec prompt>

Background map computation. Source detection at each scale...

...their matching, and fit to y(a). New background map with sources removed. Source detection using new background...

...and final source properties: significance, position, count rate, size, ...

All done!

105



